

## On comparison of exact and series solutions for thin film flow of a third-grade fluid

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### SUMMARY

The present investigation derives the exact and series solutions for steady thin film flow of a third-grade fluid. The series solution is constructed by a homotopy analysis method. The obtained solutions are compared and an excellent agreement between these is achieved. Copyright © 2009 John Wiley & Sons, Ltd.

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### 1. INTRODUCTION

Over the last four decades, the analytic solutions to flows of non-Newtonian fluids have attracted the attention of various researchers [1–10]. The literature dealing with such solutions is scarce. This is in fact due to fairly complicated constitutive equations of non-Newtonian fluids. These equations involve a number of complex parameters that in general add more number of terms and increase the order of the governing equations. In spite of all these challenges some researchers in the field [11–20] are recently engaged in developing the analytic solutions. Very recently, Hayat *et al.* [21] provide exact solutions for thin film flow of a third-grade fluid down an inclined plane.

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The purpose of the present communication is to provide the series solution of the problem considered in [21]. The series solution is given by a homotopy analysis method (HAM) developed by Liao [22, 23]. Convergence of the obtained series solution is explicitly discussed. In addition, an exact solution by incorporating typo mistake is included. Finally, the numerical values are tabulated in order to show the comparison between the exact and homotopy solutions. Like several previous attempts [24–34], the constructed homotopy solution here yields reliable results.

## 2. PROBLEM STATEMENT AND EXACT SOLUTION

In this section, we reconsider the thin film flow problem in a third-grade fluid down an incline plane of inclination  $\alpha \neq 0$  for the homotopy solution [21]. The surface tension is neglected and ambient air is taken stationary. Thickness of the thin film is kept uniform. Neglecting the pressure gradient, dimensionless problem through conservations of mass and momentum is in the form [21]

$$\frac{d^2u}{dy^2} + 6\beta \left( \frac{du}{dy} \right)^2 \frac{d^2u}{dy^2} + 1 = 0 \quad (1)$$

$$u(0) = 0, \quad u'(1) + 2\beta(u'(1))^3 = 0 \quad (2)$$

where

$$y = \delta y^*, \quad u = \frac{\delta^2 \rho g \sin(\alpha)}{\mu} u^*, \quad \beta^* = \frac{3\delta^2 \rho^2 g^2 \sin^2(\alpha)}{\mu^3} \beta$$

and asterisks have been dropped for simplicity. In the above expressions,  $\mu$  is the dynamic viscosity,  $g$  is the gravity,  $\rho$  is the density and  $\beta (= \beta_2 + \beta_3) > 0$ ,  $\beta_i$  ( $i = 2, 3$ ) is the material constants. It is pointed out that an exact solution of the problem consisting of Equations (1) and (2) is obtained in the study [21]. However, the presented exact solution has an error due to typo graphical mistake. The correct form of the exact solution is

$$u_{\text{Exact}}(y) = \frac{9(-y+1)}{8(6)^{2/3}} \left( \sqrt[3]{\frac{\sqrt{81(-y+1)^2 + \frac{6}{\beta}} - 9(-y+1)}{\beta}} - \sqrt[3]{\frac{\sqrt{81(-y+1)^2 + \frac{6}{\beta}} + 9(-y+1)}{\beta}} \right) \\ + \frac{1}{24(6)^{2/3}} \sqrt{81(-y+1)^2 + \frac{6}{\beta}} \left( \sqrt[3]{\frac{\sqrt{81(-y+1)^2 + \frac{6}{\beta}} + 9(-y+1)}{\beta}} \right)$$

$$\begin{aligned}
& + \sqrt[3]{\frac{\sqrt{81(-y+1)^2 + \frac{6}{\beta} - 9(-y+1)}}{\beta}} + \frac{9}{8(6)^{2/3}} \left( \sqrt[3]{\frac{\sqrt{81 + \frac{6}{\beta} + 9}}{\beta}} - \sqrt[3]{\frac{\sqrt{81 + \frac{6}{\beta} - 9}}{\beta}} \right) \\
& - \frac{1}{24(6)^{2/3}} \sqrt{81 + \frac{6}{\beta}} \left( \sqrt[3]{\frac{\sqrt{81 + \frac{6}{\beta} + 9}}{\beta}} + \sqrt[3]{\frac{\sqrt{81 + \frac{6}{\beta} - 9}}{\beta}} \right) \quad (3)
\end{aligned}$$

In the following section, we develop the series solution of the problem.

### 3. SOLUTION BY HAM

By Equation (1) and the boundary conditions (2), solution can be expressed in the form

$$u(y) = \sum_{m=1}^{+\infty} a_m y^m \quad (4)$$

where  $a_m$  is a coefficient to be determined later. According to the *rule of solution expression* denoted by Equation (4) and the boundary conditions (2), the quadratic approximation

$$u_0(y) = \varepsilon \left( -y + \frac{y^2}{2} \right) \quad (5)$$

can be chosen as the initial approximation to  $u(y)$ , where  $\varepsilon < 0$  is a coefficient to be determined later. An auxiliary linear operator  $\mathcal{L}$  is defined by

$$\mathcal{L}[\phi(y; p)] = \left( \frac{\partial^2}{\partial y^2} \right) \phi(y; p) \quad (6)$$

which satisfy

$$\mathcal{L}[C_1 + C_2 y] = 0 \quad (7)$$

in which  $C_1$  and  $C_2$  are constants. Considering Equation (1), the nonlinear operator is given by

$$\mathcal{N}[\phi(y; p)] = \frac{\partial^2 \phi}{\partial y^2} + 6\beta \left( \frac{\partial \phi}{\partial y} \right)^2 \frac{\partial^2 \phi}{\partial y^2} + 1 \quad (8)$$

and the homotopy is constructed as follows:

$$\mathcal{H}[\phi(y; p)] = (1-p)\mathcal{L}[\phi(y; p) - u_0(y)] - \hbar p \mathcal{N}[\phi(y; p)] \quad (9)$$

where  $\hbar \neq 0$  is the convergence-control parameter [22, 23]. Setting  $\mathcal{H}[\phi(y; p)] = 0$ , the zero-order deformation problem is

$$(1-p)\mathcal{L}[\phi(y; p) - u_0(y)] = \hbar p \mathcal{N}[\phi(y; p)]$$

$$\phi(0; p) = 0, \quad (1-p) \left[ \frac{\partial \phi(y; p)}{\partial y} \right]_{y=1} + \hbar p \left[ \frac{\partial \phi(y; p)}{\partial y} + 2\beta \left( \frac{\partial \phi(y; p)}{\partial y} \right)^3 \right]_{y=1} = 0 \quad (10)$$

where  $p \in [0, 1]$  is an embedding parameter. When the parameter  $p$  increases from 0 to 1, the solution  $\phi(y; p)$  varies from  $u_0(y)$  to  $u(y)$ . If this continuous variation is smooth enough, the Maclaurin's series with respect to  $p$  can be constructed for  $\phi(y; p)$ , and further, if this series is convergent at  $p = 1$ , we have

$$u(y) = u_0(y) + \sum_{m=1}^{+\infty} u_m(y) = \sum_{m=0}^{+\infty} \phi_m(y, \hbar)$$

$$u_m(y) = \left. \frac{1}{m!} \frac{\partial^m \phi(y; p)}{\partial p^m} \right|_{p=0} \quad (11)$$

Differentiating Equation (10) and related conditions  $m$  times with respect to  $p$ , then setting  $p = 0$ , and finally dividing by  $m!$ , the  $m$ th-order deformation problem can be written as

$$\mathcal{L}[u_m(y) - \chi_m u_{m-1}(y)] = \hbar R_m(y) \quad (m = 1, 2, 3, \dots) \quad (12)$$

$$u_m(0) = 0$$

$$u'_m(1) - \chi_m u'_{m-1}(1) + \hbar \left( u'_{m-1}(1) + 2\beta \sum_{n=0}^{m-1} \left( \sum_{i=0}^n u'_i(1) u'_{n-i}(1) \right) u'_{m-n-1}(1) \right) = 0 \quad (13)$$

where

$$R_m(y) = u''_{m-1} + 6\beta \sum_{n=0}^{m-1} \left( \sum_{i=0}^n u'_i u'_{n-i} \right) u''_{m-n-1} + (1 - \chi_m)$$

and prime denotes differentiation with respect to  $y$  and

$$\chi_m = \begin{cases} 0, & m \leq 1 \\ 1, & m > 1 \end{cases}$$

The general solution of Equation (12) is of the form

$$u_m(y) = \hat{u}_m(y) + C_1 + C_2 y \quad (14)$$

where  $\hat{u}_m(y)$  is particular solution of Equation (12),  $C_1$  and  $C_2$  are constants that will be obtained by conditions (13).

At the  $N$ th-order approximation, the analytic solution of Equation (1) is

$$u(y) \approx U_N(y) = \sum_{i=0}^N u_i(y) \quad (15)$$

Note that the auxiliary parameter  $\hbar$  is employed to adjust the convergence region of the series (15) in the homotopy analysis solution. By  $\hbar$ -curve, it is straightforward to choose an appropriate range for  $\hbar$  which ensures the convergence of the solution series. As pointed out by Liao [22], the appropriate region for  $\hbar$  is a horizontal line segment.

#### 4. NUMERICAL RESULTS

We use the widely applied symbolic computation software MATHEMATICA to solve Equation (12) and find that  $\phi_m(y, \hbar)$  has the following structure:

$$\phi_n(y, \hbar) = \sum_{m=1}^{2n+2} \Phi_{n,m}(\varepsilon, \hbar) y^m, \quad n \geq 0$$

For example, we can find that

$$\Phi_{1,1} = -((1+\hbar)-1) - \varepsilon(1+\hbar) - 10\hbar\varepsilon^3$$

$$\Phi_{2,1} = -((1+\hbar)^2-1) - \varepsilon(1+\hbar)^2 - 30\hbar^2\varepsilon^2 - 20\hbar\varepsilon^3 - 40\hbar^2\varepsilon^3 - 300\hbar^2\varepsilon^5$$

and so on. The parameter  $\varepsilon$  is used to optimize the initial approximation of  $u(y)$ . Here, for choosing  $\varepsilon$  we minimize the absolute residual error of Equation (1) at  $y=0$  for  $u_0(y)$  and each  $\beta$ . Table I shows the obtained values for  $\varepsilon$  for some examples.

By means of the so-called  $\hbar$ -curve, it is straightforward to choose an appropriate range for  $\hbar$ , which ensures the convergence of the solution series. As pointed out by Liao [22], the appropriate region for  $\hbar$  is a horizontal line segment. We can investigate the influence of  $\hbar$  on the convergence of  $u'(0)$ , by plotting the curve of it versus  $\hbar$ , as shown in Figures 1 and 2 for some examples. We can see that by decreasing  $\beta$ , the distance of reasonable interval for  $\hbar$  increases. By considering the  $\hbar$ -curve we can obtain the reasonable interval for  $\hbar$  in each case. In addition, by computing the error of norm 2 for two successive approximation of  $U_N(y)$ , we can obtain the best value for  $\hbar$  for every  $\beta$ . Table I shows the chosen values for  $\hbar$  for some examples and Figure 3 shows the HAM solutions for  $U_{20}(y)$  for these values of  $\hbar$ .

The so-called homotopy-Padé technique (see [22]) is employed, which greatly accelerates the convergence. The  $[r, s]$  homotopy-Padé approximations of  $u'(0)$  and  $u''(0)$ , according to (11), are

Table I. Results for  $\varepsilon$  and  $\hbar$ .

$\beta$	$\frac{1}{3}$	$\frac{2}{3}$	1	5	10	20
$\varepsilon$	-0.59	-0.5	-0.451	-0.287	-0.22	-0.189
$\hbar$	-0.490	-0.399	-0.352	-0.181	-0.126	-0.097

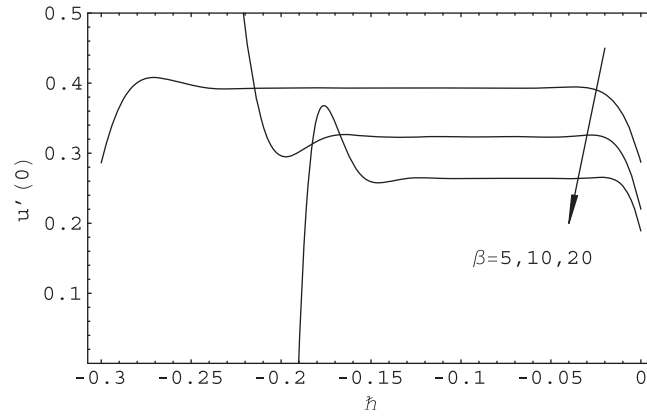


Figure 1. The  $h$ -curves of  $u'(0)$  for the 20th-order approximation.

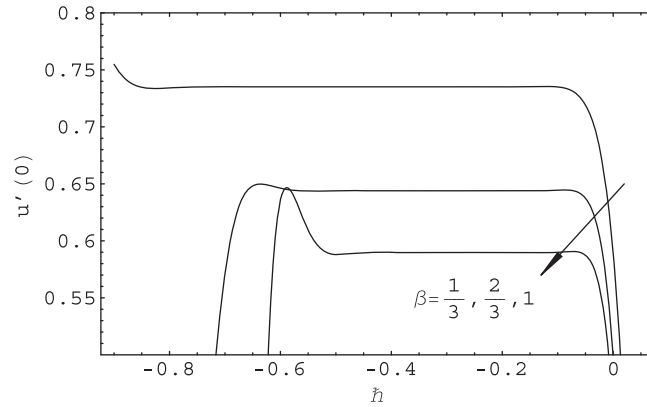


Figure 2. The  $h$ -curves of  $u'(0)$  for the 20th-order approximation.

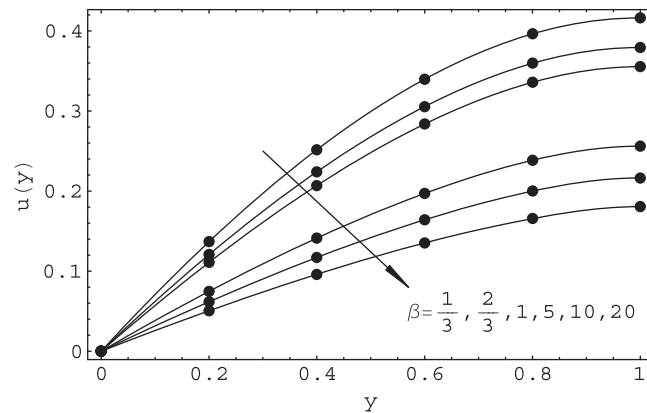


Figure 3. Dimensionless velocity profiles with different values of  $\beta$  for the 20th-order approximation. Symbols: exact solution from (3); solid curves: HAM solution.

Table II. Results for [10, 10] homotopy-Padé approach for  $u'(0)$  and  $u''(0)$ .

$\beta$	$u'(0)$	$u'_{\text{Exact}}(0)$	$u''(0)$	$u''_{\text{Exact}}(0)$
$\frac{1}{3}$	0.735139	0.735139	-0.480571	-0.480571
$\frac{2}{3}$	0.643955	0.643955	-0.376122	-0.376122
1	0.589755	0.589755	-0.323954	-0.323954
5	0.393003	0.393003	-0.177508	-0.177508
10	0.323415	0.323418	-0.137438	-0.137439
20	0.264000	0.264001	-0.106796	-0.106797

formulated by

$$\frac{\sum_{k=0}^r \phi'_k(0, \hbar)}{1 + \sum_{k=1}^s \phi'_{r+k+1}(0, \hbar)}, \quad \frac{\sum_{k=0}^r \phi''_k(0, \hbar)}{1 + \sum_{k=1}^s \phi''_{r+k+1}(0, \hbar)}$$

respectively. In many cases, the  $[r, r]$  homotopy-Padé approximation does not depend upon the auxiliary parameter  $\hbar$ . Table II shows the [10, 10] homotopy-Padé results for  $u'(0)$  and  $u''(0)$  for some examples.

## 5. FINAL REMARKS

In the present study, both exact and homotopy analysis solutions are first derived and then compared. It is explicitly shown that an agreement between the derived solutions is excellent. Hence, the presented analysis tends further confidence and reliability of HAM.

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